

ANGt101

goniometer for high loads providing Θ -positioning

Technology			
travel mechanism	inertial piezo drive		
Size and Dimensions			
footprint; height	24 x 24; 11 mm		
maximum size	28.6 x 24; 11.8 mm		
distance center of rotation to bottom	51 mm (above center)		
Coarse Positioning Mode			
travel (step mode)	6.6°		
typical minimum step size	0.1 m° @ 300 K, 0.02 m° @ 4 K		
maximum speed (@ 300 K, no load)	approx. 1 °/s		
Fine Positioning Mode			
scan range	no fine positioning capability		
Materials (non-magnetic)			
positioner body	Titanium (other materials on request)		
actuator	PZT ceramics		
connecting wires	insulated twisted pair, Cu		
weight	18 g		
Load			
maximum vertical load	100 g		
maximum static forces along the axis	3 N		
maximum dynamic force along the axis	2 N		
Mounting			
frontside mounting	two through holes for M2		
backside mounting	two threads M2.5 x 6 mm		
load mounting	six threads M2 x 3 mm		
Article Numbers			
/RT Version	1002732	/LT Version	1002735
/HV Version	1002733	/LT/HV Version	1002736
/UHV Version	1002734	/LT/UHV Version	1002737
Compatibility with Electronics			
ANC106 piezo step controller	/RT version only		
ANC300 piezo positioning controller	all versions		

Working Conditions		
mounting orientation	axis perpendicular to gravity	
magnetic field range	0 .. 31 T	
temperature range (/RT, /HV, /UHV)	0 .. 100 °C	
temperature range (/LT, /LT/HV, /LT/UHV)	10 mK .. 373 K	
max. bake out temperature (/UHV, /LT/UHV)	150 °C	
minimum pressure (/RT, /LT)	1E-4 mbar	
minimum pressure (/HV, /LT/HV)	1E-8 mbar	
minimum pressure (/UHV, /LT/UHV)	5E-11 mbar	
Connectors and Feedthroughs		
	/RT, /LT Versions	all /HV, /UHV Versions
connector type	2-pole pin plug, ø 0.5 mm, d = 2 mm, integrated connector	2-pole pin plug (PEEK), ø 0.5 mm, d = 2 mm, 30 cm cable with connector
electrical feedthrough solution	COC230/LT	COC230/HV, COC230/UHV
Temperature Dependent Data		
	@ 300K	@ 4K (only /LT versions)
input voltage range	0 .. +100 V	0 .. +100 V
typical actuator capacitance	1050 nF	150 nF
typical step size (min .. max)	0.1 .. 3 m°	0.02 .. 0.5 m°
fine positioning range	---	---
Accuracy of Movement		
repeatability of step sizes	typically 5 % over full range	
forward / backward step asymmetry	typically 5 %	
Position Encoder		
encoder options	/NUM, /RES	

Drawings

