

## ANRv51

compact rotary stepper positioner with horizontal axis for 1" setups

Technology	
travel mechanism	inertial piezo drive

Size and Dimensions	
footprint; height	10 x 20; 21 mm
through hole in the middle of the axis	Ø 1.5 mm

Coarse Positioning Mode	
travel (step mode)	360° endless, both directions
typical minimum step size	1 m° @ 300 K, 0.5 m° @ 4 K
maximum speed (@ 300 K, no load)	approx. 10°/s

Fine Positioning Mode	
scan range	40 m° @ 300 K, 6 m° @ 4 K
scan resolution	µ° resolution

Materials (non-magnetic)	
positioner body	Titanium (other materials on request)
actuator	PZT ceramics
connecting wires	insulated twisted pair, Cu
weight	10 g

Load	
maximum vertical load	20g
maximum static torque around axis	0.3 Ncm
maximum dynamic torque around axis	0.2 Ncm
maximum torque perpendicular to axis	5 Ncm

Mounting	
frontside mounting	---
backside mounting	two threads M2 x 3 mm
load mounting	two threads M1.6 x 1 mm

Article Numbers			
/RT Version	1003297	/LT Version	1003298
/HV Version	1003299	/LT/HV Version	1003301
/UHV Version	1003300	/LT/UHV Version	1003302

Compatibility with Electronics	
ANC106 piezo step controller	/RT version only
ANC300 piezo positioning controller	all versions

Working Conditions	
mounting orientation	axis horizontal
magnetic field range	0 .. 31 T
temperature range (/RT, /HV, /UHV)	0 .. 100 °C
temperature range (/LT, /LT/HV, /LT/UHV)	10 mK .. 373 K
max. bake out temperature (/UHV, /LT/UHV)	150 °C
minimum pressure (/RT, /LT)	1E-4 mbar
minimum pressure (/HV, /LT/HV)	1E-8 mbar
minimum pressure (/UHV, /LT/UHV)	5E-11 mbar

Connectors and Feedthroughs	/RT, /LT Versions	all /HV, /UHV Versions
connector type	2-pole pin plug, Ø 0.5 mm, d = 2 mm,	2-pole pin plug (PEEK), Ø 0.5 mm, d = 2 mm,
connector type	30 cm cable with connector	30 cm cable with connector
electrical feedthrough solution	VFT/LT	VFT/HV, VFT/UHV

Temperature Dependent Data	@ 300K	@ 4K (only /LT versions)
input voltage range	0 .. +60 V	0 .. +60 V
typical actuator capacitance	2050 nF	400 nF
typical step size (min .. max)	1 .. 50 m°	0.5 .. 25 m°
fine positioning range	40 m°	6 m°

Accuracy of Movement	
repeatability of step sizes	typically 5 % over full range
forward / backward step asymmetry	typically 5 %

Position Encoder	
encoder options	/RES

